



## MAIN FEATURES

Thanks to the magnetic technology, EMI 40 series is suitable for harsh environment applications such as marble and glass working machines, washing systems and generally for industrial automation.

- · 3 channel encoder (A / B / Z) up to 2048 ppr
- · Power supply up to +28 V DC with several electrical interfaces available
- · Cable output, connectors available on cable end
- · Compact dimensions
- · Solid shaft diameter up to 6 mm
- · Sturdy construction due to separated chambers design
- · Wide operating temperature -25° ... +100°C (-13° ... +212°F)







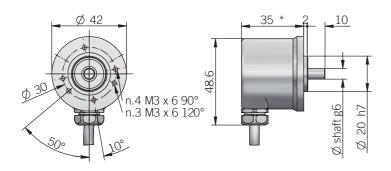


ORDERING CODE	EMI	40A	1024	Z	5	L	6	X	3	P	R	. XXX
	SERIES magnetic incremental encoder series EMI clamping flange ø 20	MODEL mm 40A										
		RES ppr from 2 e available	pulses list	O PULSE								
		V	vithout zer	o pulse S o pulse Z	ouppiv							
	(wi	(witl th L electric	h L electrica cal interface	ıl interface) e) 8 24 V								
					TRICAL IN	TERFACE sh-pull P e driver L						
							mm 4 mm 6					
						E	ENCLOSUR	IP 64 X IP 66 S				
								<b>X ROTATIO</b> (IP 66) 30 (IP 64) 60	00 rpm 3 00 rpm 6			
		ı	preferred ca	ble lengths	1,5/2/3/	5 / 10 m, to			<b>OUTF</b> ard length FION TYPE (e	g. PR5)		
											axial A radial R	
												VARIANT



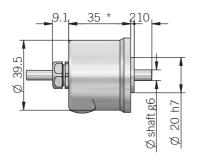
custom version XXX

## 40 A radial cable output



recommended mating shaft tolerance H7 dimensions in mm

## 40A axial cable output



\* IP66 + 7 mm

ELECTRICAL SPECIFICATIONS			
Resolution	from 2 to 2048 ppr		
Power supply <sup>1</sup>	$5 = 4,5 \dots 5,5 \text{ V DC}$ $5/28 = 4,75 \dots 29,4 \text{ V DC}$ $8/24 = 7,6 \dots 25,2 \text{ V DC}$ (reverse polarity protection)		
Current consumption without load	80 mA max		
Max load current	current 20 mA / channel		
Electrical interface <sup>2</sup>	push-pull / line driver HTL (AEIC-7272) line driver RS-422 (AELT-5000 or similar)		
Max output frequency	205 kHz		
Counting direction	A leads B clockwise (shaft view)		
Accuracy	$\pm$ 0,35° typical / $\pm$ 0,50° max		
Electromagnetic compatibility	according to 2014/30/EU directive		
RoHS	according to 2011/65/EU directive		
UL / CSA	certificate n. E212495		

CONNECTIONS		
Function	Cable P	Cable L
+V DC	red	red
0 V	black	black
A+	green	green
A-	/	brown or grey
B+	yellow	yellow
B-	/	orange
Z+	blue	blue
Z-	/	white
÷	shield	shield

MECHANICAL SPECIFICATIONS				
Shaft diameter	ø 4 / 6 mm			
Enclosure rating	X = IP 64 (IEC 60529) S = IP 66 (IEC 60529)			
Max rotation speed	IP 66 - 3000 rpm IP 64 - 6000 rpm			
Max shaft load <sup>3</sup>	5 N axial / radial			
Shock	50 G, 11 ms (IEC 60068-2-27)			
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)			
Moment of inertia	0,5 x 10 <sup>-6</sup> kgm <sup>2</sup> (12 x 10 <sup>-6</sup> lbft <sup>2</sup> )			
Starting torque (at +20°C / +68°F)	< 0,02 Nm (2,83 Ozin) IP 64 < 0,05 Nm (7,10 Ozin) IP 66			
Bearing stage material	EN-AW 2011 aluminum			
Shaft material	1.4305 / AISI 303 stainless steel			
Housing material	painted aluminum			
Bearings	n.2 ball bearings			
Bearing lifetime	109 revolutions			
Operating temperature <sup>4, 5</sup>	-25° +100°C (-13° +212°F)			
Storage temperature <sup>5</sup>	-25° +85°C (-13° +185°F)			
Weight	150 g (5,29 oz)			

<sup>&</sup>lt;sup>1</sup> as measured at the transducer without cable influences

## **RESOLUTIONS**

2 - 4 - 8 - 10 - 16 - 20 - 32 - 40 - 64 - 80 - 100 - 125 - 128 - 200 - 250 - 256 - 400 - 500 - 512 - 1024 - 2048





 $<sup>^{\</sup>rm 2}$  for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

<sup>&</sup>lt;sup>3</sup> maximum load for static usage

<sup>&</sup>lt;sup>4</sup> measured on the transducer flange

<sup>&</sup>lt;sup>5</sup> condensation not allowed